

MOST Project - 3

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TECHNICAL PROGRESS REPORT FOR C/P ARRAY SONAR DEVELOPMENT PROGRAM FOR APRIL 1966

MAY 1966

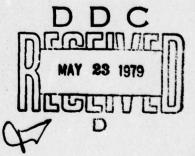
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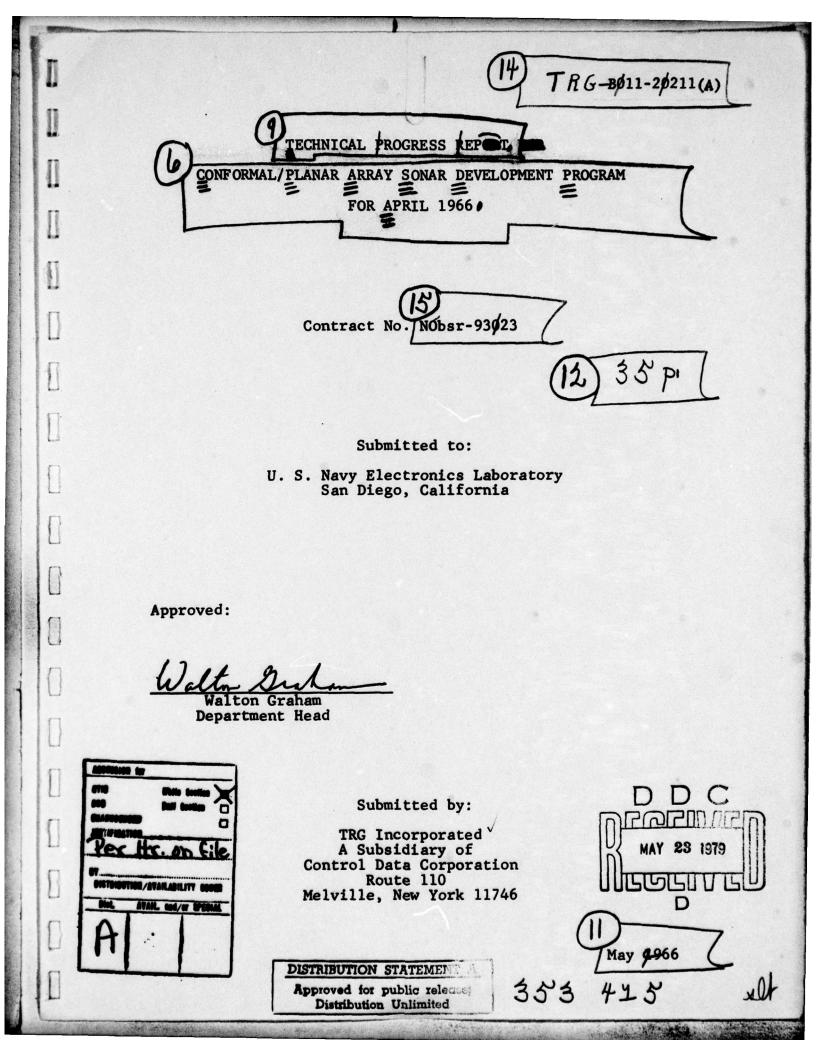


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Major technical areas of activity for the month of April were as follows:

1000--SYSTEM ANALYSIS AND INTEGRATION

1100: SONAR SYSTEM AND TOTAL SYSTEM ANALYSIS

1. Sonar Prediction

The report describing the results of the stepped RDT study was completed and submitted to NEL for approval.

The modified pattern function to simulate vertical shading has been installed into the OCEAN SWEEPER. The vertical shading is simulated by multiplying the sidelobes by an input constant; the broadening of the beam is accomplished by reducing the spacing between vertical elements thereby achieving a smaller effective height for the sonar. It is anticipated that the OCEAN SWEEPER program will be run with and without shading for the surface-duct prediction problem supplied by NEL. The report summarizing the direct path analysis should be ready before the end of May. It is currently anticipated that A. Novick will visit NEL during the third week of May and a preliminary copy of the results supplied to the Project Office at time.

The report describing the TRG ocean model used for the OCEAN SWEEPER program³ was completed and submitted to NEL for approval.

A report describing the forthcoming bistatic echoranging study is in progress and should be sent to NEL on 15 May 1966. A possible technique for efficiently generating the bistatic reverberation contour on a boundary has been developed. The method is an extension of the techniques used in the current OCEAN SWEEPER program and will be described in the report. At present, work is progressing in developing the organization of the required computer program(s) as well as associated analytical techniques for evaluating the reverberation integral. In addition, it appears that due to the "poor" behavior of the pattern function, and the discontinuous nature of the reverberating area, it

will not be practical to use standard numerical integration techniques (e.g., Simpson) and other schemes will have to be developed.

2. Surface-Duct Model

Work is in progress to develop computerized method for finding all surface-duct ray paths of interest in a given problem. Once this is accomplished, it will be possible to automate the surface-duct sonar prediction model. Current estimates are that it will take approximately another three months to complete this effort.

3. System Effectiveness

The report on the Simplified Performance Measure⁵ was rewritten and submitted to NEL for approval.

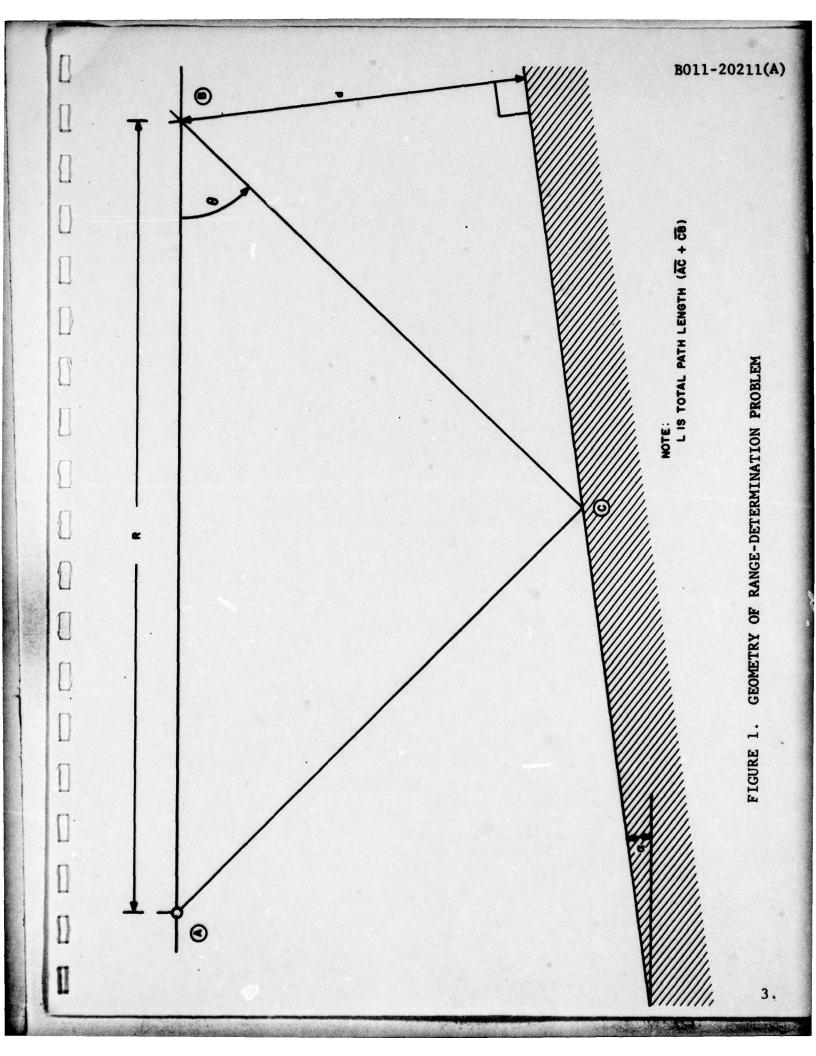
The Second NMSE System Performance Effectiveness Conference held on April 21 and 22 in Washington, D.C. was attended by Messrs. L. Chin, W. Landauer and A. Novick. Essentially, the conference stressed the need for systems effectiveness studies before PDP; in fact, DOD approval will not be granted to any system where a trade-off analysis has not been performed.

An investigation has been conducted on the effect of bottom slope on the determination of target range from travel time information in an isovelocity medium. For this problem, it is assumed that the travel time for the echo path, the perpendicular distance from the ship to the bottom, the slope of the bottom (denoted by α) and the velocity of sound are known. The geometry is illustrated in Figure 1.

We shall denote the slant range to the target by L, which is given by L = 1/2 cT, where T is the travel time and c is the speed of sound. By trigonometric identities and the law of sines, one may obtain the following expressions

$$R = \frac{L \cos(\theta + \alpha)}{\cos \alpha}$$

$$\sin(\Theta+2\alpha) = \frac{2d \cos\alpha}{L}$$



By manipulating the above expressions and restricting our interest to relatively small values of α , it is found that

$$R \doteq L \cos\theta_0 + 2d \sin\alpha$$

where

$$\cos\theta_0 = \frac{L^2 - 4d^2}{L}$$
, and $\sin^2\alpha \tan^2\theta \ll 2$

From the last equations it is seen that the expression for the target range is composed of two terms. The first term is simply the range to the target assuming a horizontal bottom; the second term represents the deviation from this nominal range. It is somewhat startling to note that the range error resulting from the bottom slope is only a function of the water depth and is independent of the range to the target!

A report on this investigation is in progress and should be available by the end of ${\rm May}^6$.

Work is proceeding on the development of an effectiveness model for the optimization of the conformal/planar array design. Leonard Chin has reviewed the available literature and is setting up the effectiveness model for the sonar investigation.

Currently, Mr. Chin is in the process of writing a report on the theoretical phase of the problem⁷. The report will consist of three parts. Part one will discuss the theory and applications of the Calculus of Variations; part two, the Theory of Maximum and Minimum, and part three, the Dynamic Programming technique. This report is estimated to be finished by the end of May 1966. Immediately after the completion of this report, Mr. Chin will start the investigation on the Procedure phase of the problem.

Mr. L. Cohen from NEL Project Office, visited TRG on April 25 and 26 to review progress being made in the systems analysis area. On April 26, Mr. Cohen and several members from TRG participated in C/P system effectiveness discussions at the Navy Applied Science Laboratory. These discussions were only preliminary and further discussions will be held during the early part of May.

4. ASW Simulation Computer Program

The memory and speed capabilities of current digital computers require that an apriori selection of the depth of detail required for a realistic ASW simulation program be made. The selection made largely determines the organization of the computer program. During January and February two versions of the mission effectiveness computer program were written or partially written which were organized about six or seven functional areas which are involved in an ASW mission, and which used a fixed memory allocation scheme. These programs proved to be inadequate to handle the details of a complex ASW mission. In March, the current program was begun. It is organized around ten functional ASW areas, and uses a dynamic memory allocation scheme where the storage required for each function is drawn from a pool when it is needed and returned to the pool when it has served its purpose. This scheme complicates the programming considerably and is less efficient as far as the storage of a given item of information. It is, however, more efficient in an overall sense because of the dynamic sharing which takes place in time as the action being simulated takes place. As of the end of April, the pilot version of this program has been written and debugging is underway.

1200: TOTAL SYSTEM, SUBSYSTEM, AND COMPONENT RELIABILITY AND MAINTAINABILITY

During the meeting between TRG and NASL personnel, NASL's philosophy of System Effectiveness was discussed. As a result of this meeting, a list and description of specific work tasks to be performed by TRG is being prepared. This list will conform to the new requirements contained in Section 10 (Revised) of the Technical Development Plan. The tentative list of work tasks is as follows:

- 1. Develop system block diagram with various block configurations.
- 2. Develop effectiveness model
- 3. Perform system performance comparisons
- 4. Assignment of component availability goals
- 5. Develop component failure rate matrix
- 6. Develop component repair rate matrix
- 7. Derive and solve availability models
- 8. Develop reliability program plan
- 9. Develop maintainability progress plan
- 10. Develop RFQ evaluation plan (for R/M only)
- 11. Perform special studies/tests as directed by NASL
- 12. Investigate previous sonar problem areas
- 13. Coordinating FISC effort with NASL
- 14. Human engineering support
- 15. Development of packaging technique
- 16. Provide Liaison engineering support at NASL
- 17. Manpower estimation.

The reliability aspects of the PRIMAG method of beam forming were reviewed. Some of the aspects considered were:

- 1. Effects and safeguards against shock.
- 2. Effects and safeguards against dirt contamination.
- 3. Bearing type lubricant and life under shipboard environments.
- 4. Redundant drums.
- Drive motor type and life under shipboard environments.

A review of the experience of other drum-type devices under operational conditions will be made by contact with Hughes and Sperry personnel. The forthcoming report on evaluation of the $PRIMAG^8$ will contain a section pertaining specifically to reliability.

1300: SYSTEM INTEGRATION

System integration manpower was discussed at a meeting at NEL. A proposed organization chart for the R/M and System Integration team was discussed with the PTD. The need for possible additional future manpower above that shown on the chart in the FISC areas and in the area of specification writing was mentioned to TRG, and TRG is planning to make this manpower available, within funding constraints, as soon as the need arises. Personnel assigned to the various areas are familiarizing themselves with the system components for which they will be responsible. A list of reports generated by GD/E and GE has been reviewed, and those considered important for TRG use in systems integration activities have been requested by TRG.

1400: FAULT LOCATION AND SELF-CHECK SUBSYSTEM

Effort expended during April consisted primarily of study of the basic factors affecting the selection of Fault Isolation and Self-Checking (FISC) implementation. A preliminary set of objectives of FISC implementation and specific requirements for the FISC study efforts were established. These objectives and requirements have been drafted and are in the process of being finalized for submittal.

The objectives of the FISC program are to assure proper consideration of FISC functions during initial system design and to insure that the FISC subsystem:

- 1. Makes a maximum contribution to system availability within cost effectiveness constraints.
 - 2. Maximizes user confidence in the system.
 - 3. Reduces personnel requirements.
- 4. Has capability to contribute to shipboard performance estimations.
- Provides support for preventive and corrective maintenance.

The FISC program will include efforts to define both ESS and CF (Concept Formulations) subsystems. Information on specific test parameter requirements will be requested from each activity responsible for a specific component. Alternative approaches to FISC implementation will be considered. Requirements for stimuli generators and sensors will be defined. Test schedules will be established. Functional diagrams will be generated. Coordination of efforts and requirements will be maintained among the C/P sonar contractors and with NEL and NASL.

Effort during the month of May will include:

- 1. A study of existing FISC implementation techniques.
- Development of first iteration test specifications for transmit power drivers, receive pre-amplifiers, and the

beamformers. Requirements for testing the transducers will also be considered.

3. A technical report in this area 9 will be submitted in May.

2000 -- ARRAY

2100: PRE-AMPLIFIER

Work in progress on the converter-filter portion of the front end electronics was terminated at the beginning of the month. A report was prepared on the test results up to April and submitted to NEL as requested 10 . The filter has a 3 db bandwidth of 200 cps, 60 db stop-band attenuation and a shape factor of 2.2:1 at 60 db down. Dynamic range of the up-down converter is 90 db. Operation was in the 2 to 3 Kc band.

2200: TOLERANCES OF ARRAY ELEMENTS

The effects of random errors in the element excitations on the far field pattern will be compared for an array with a uniform excitation distribution and an array with a tapered excitation distribution. The theoretical analysis has been performed; and a computer program is being written to obtain numerical results.

1. Acoustic Effects of Bubbles

A computer program to calculate the effects of a finite number of bubbles on the sound field of one or more pistons is being debugged.

2. A-IDA

We designed a transducer element for the A-TDA activity and delivered the supporting data and the design to NEL on April 19, 1966.

All designs submitted to NEL were very similar, and the design was selected on a single criterion ($Z_{\rm oc}$ bandwidth). The $Z_{\rm oc}$ bandwidth from design to design varied approximately 10%.

We are now in the process of fabricating two of these preliminary system elements. One will be dumiload tested to establish whether its response is in agreement with the theoretical predictions, and the other will be sent to NEL when it is completed.

Our exact-invert scheme is working well and we intend

to write out the velocity distribution and/or pseudo inverse on tape for post-processing such as VA, electric field in the ceramic, efficiency, etc.

For a transducer element whose $Z_{\rm oc}$ is at least 5 times as great as the characteristic impedance the system matrix is moderate strongly diagonal and therefore amenable to an iterative scheme for inverting. Since the $Z_{\rm oc}$ will be greater than 5 times the characteristic impedance, we will implement an iterative scheme because it requires much less computing time.

2300: DUMILOAD

Experiments were performed to measure unloaded matching section impedance for both thick and thin walled tubes including an experimental determination of a known load for each case. Studies performed after previous experiments indicated a need for paying special attention to the effect of measurement errors, and this was done. The resulting experimental values were closer to the theoretical values than previously experienced. For instance, in the experimental determination of a known load using a thin walled section and the job model for the load, a value of j 1.32×10^4 was expected. The measured value was 1.54×10^2 + j 1.17×10^4 . This value is within 12% of the expected value (the small real part resulted from the phase shift observed across the temporary bonds employed to make the test setup).

Previous experiments had produced much larger discrepancies between theoretical and measured values.

Consideration was also given to the effects of laboratory acoustic noise interference when low level measurements were made.

On April 19, 1966, D. Carson of NEL and T. Defilippis of TRG discussed the redirection of the Dumiload program. As a result of that discussion, we have proceeded to reorganize our activity. The Dumiload Education Program is now centered about the preliminary system element. This element is in the process of being developed.

Dental cement was used to bond the matching section to the driving element, and the known load.

7000 -- NAVAL ARCHITECTURE AND HULL INTERFACES

7100: SEA TEST SUPPORT

Work continued on the modification and addition of equipment to the Shipboard Recording Center for the PURVIS II experiments. The cosential changes of equipment on the PURVIS for the second series of experiments are:

- (1) Removal of all PURVIS I hydrophones and associated preamplifiers. The installation of TRG 5" hydrophones and preamplifiers, and special windows in Sea Chests 1 and 2. (See Figure 2).
 - (2) Addition of four sonar transmitting elements.
- (3) Addition of four flow-flags with electrical position outputs.

The data instrumentation changes required to accomodate PURVIS II include:

- (1) Addition of four frequency sources, power amplifiers, remote controls to drive the four transmitters, and instrumentation to monitor and tape record the amplifier outputs.
- (2) Addition of band-pass filters and amplifiers to monitor hydrophone outputs resulting from simultaneous transmission from the four transmitters operating at four different frequencies.
- (3) Addition of remote controls for the excitation to the flow-flag sensors, and signal conditioning to record the output signals on the ship's motion (slow speed) tape recorder.
- (4) Addition of an Indicator-Transmitter to read the sensed velocity from an E/M velocity log instrument located on a retractable strut. One of the transmitters is mounted on the retractable strut.
- (5) Modification of cabling and recording patch panel to accommodate new hydrophones at different locations on the hull. DTMB is providing, (a) additional signal conditioning amplifiers

ACCELEROMETER

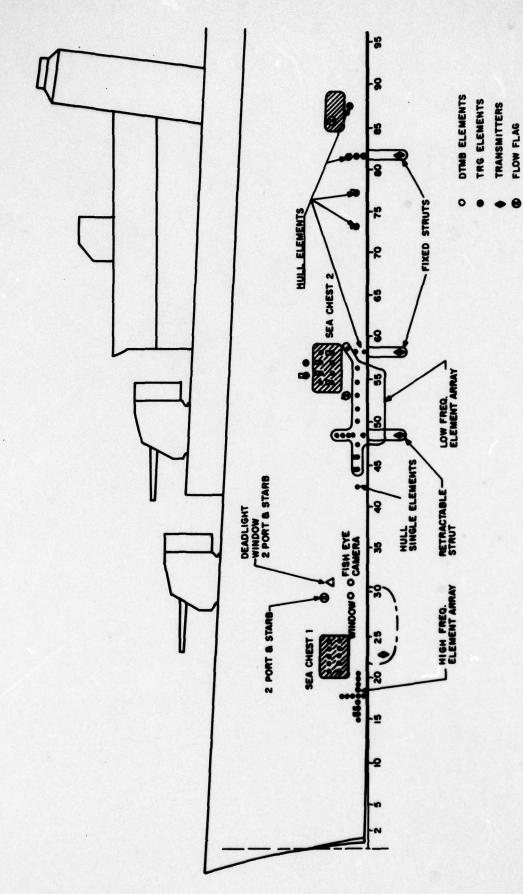


FIGURE 2. PURVIS II TRANSDUCER INSTALLATION

(SCA), and (b) input attenuators to prevent overloading of the tape record electronics. Each SCA will be directly connected to a hydrophone or accelerometer. Triaxial cables will be employed from the Recording Center bulkhead connectors to the SCA inputs with the recording patch occurring between the SCA outputs and the four high-speed tape recorders.

(6) The masker (bubble) generators have been modified to provide control and indication of air flow rate. These items will not be recorded on magnetic tape but will be manually noted.

Procurement for the instrumentation equipment described above has been completed. Fabrication and assembly of electronic chassis will be completed for shipboard installation at the Boston Naval Shipyard during the month of May.

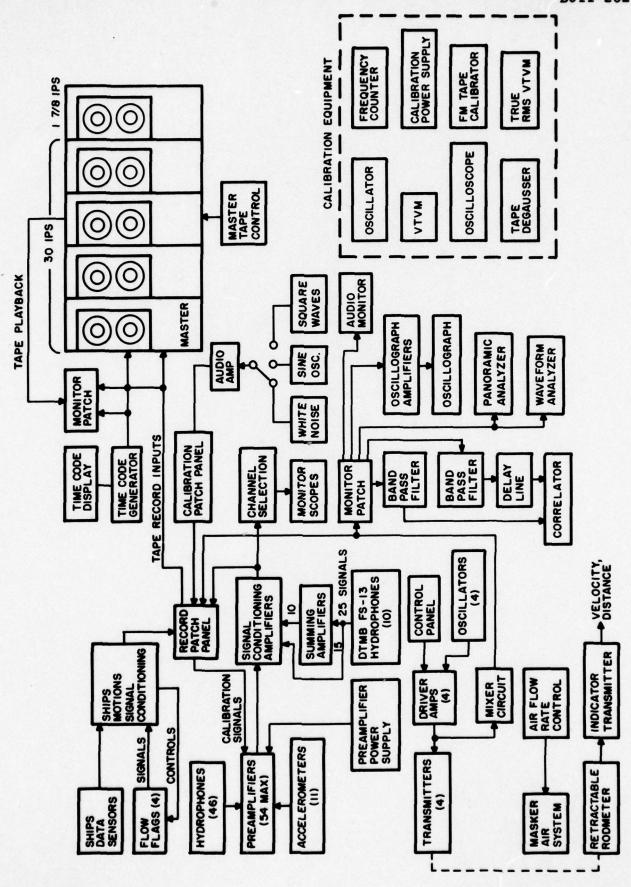
A diagram of the planned hydrophone and accelerometer installation on PURVIS is given in Figure 2. TRG hydrophones are mounted in low and high frequency arrays, on the hull, and in Sea Chest No. 2. DTMB hydrophones (FS-13) are mounted in Sea Chest No. 1.

A block diagram of the PURVIS II instrumentation is given in Figure 3.

1. PURVIS I DATA REDUCTION

Data recorded on PURVIS I runs are being processed at NEL. The data reduction being performed includes auto- and cross-correlations, power spectrum and time histories. Samples of header records, cross-correlation print-out and plot, and auto-correlation print-outs are shown in Figures 4a through 4e.

A sample analog power spectrum is shown in Figure 5. Four spectra taken at four different ship's velocities are shown for a single hydrophone. An interim report containing selected spectral density data reduction results has been prepared 11 and will be issued during May, 1966.

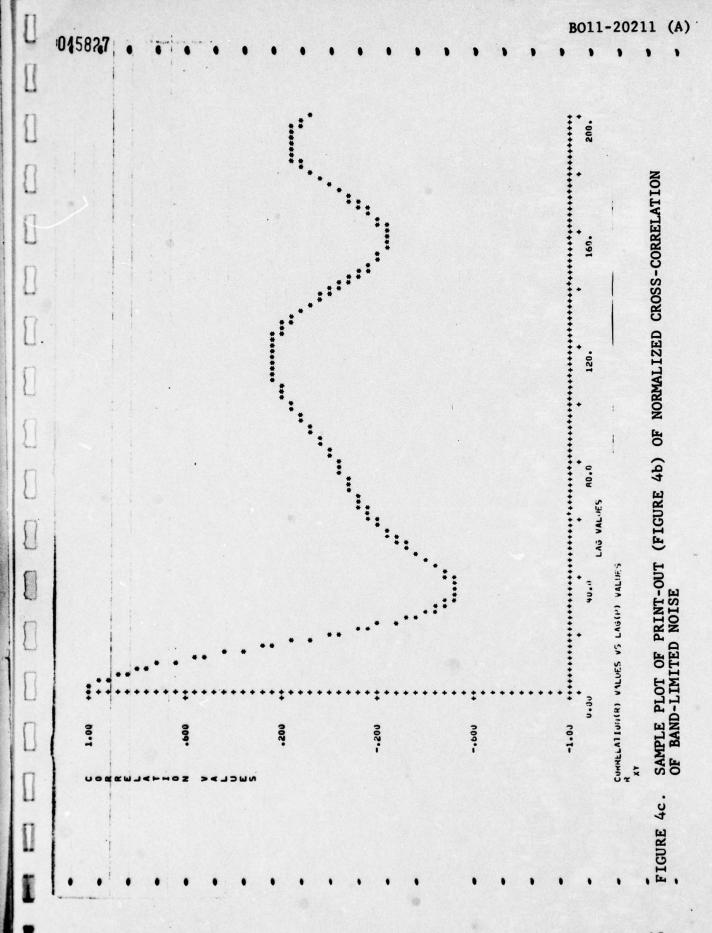


15.

BLOCK DIAGRAM OF PURVIS II INSTRUMENTATION

FIGURE 3.

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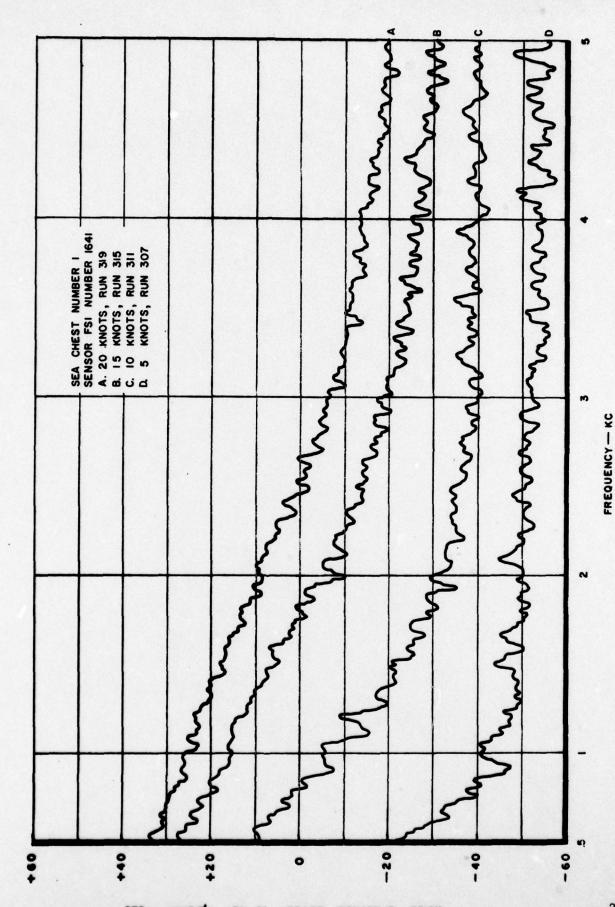
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SAMPLING RATE DIVIDE SETTING IS	•
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HEADER RECORD FOR AUTO-CORRELATION OF SEA DATA (HYDROPHONES: FS1; NO'S 1665 and 1657 LOCATED IN SEA CHEST 2. SPEED: 20 KNOTS: HEADING: 0°, RELATIVE TO SEA; ELEMENT SEPARATION: 3/4") FIGURE 4d.

FIGURE 4e. AUTO-CORRELATION PRINT-OUT FOR HEADER RECORD OF FIGURE 4d



21.

FIGURE 5.

SAMPLE ANALOG POWER SPECTRUM FOR FOUR DIFFERENT SHIP VELOCITIES

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	L		0.000	62.500	93.750	125.000	187.500	218.750	281.250	312.500	343.750	375.000	437.500	468.750		000.000	562.500	593.750	625.000	656.250	718.750	750.000	-781.250	812.500	843.750	906.250	937.500	968.750	1000.000	1031.250	1093-750	1125.000	1156.250	1187.500

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0

FIGURE 6.

SPEED: 20 KNOTS; 0° HEADING RELATIVE TO SEA; ELEMENT SEPARATION 3/4" CROSS-SPECTRAL DENSITY PRINT-OUT; RUN 317 CHANNEL X: FS1 1665, SEA CHEST 2 CHANNEL Y: FS1 1657, SEA CHEST 2

A sample digital power spectrum print-out for band limited hydrophone data is shown in Figure 6_{\bullet}

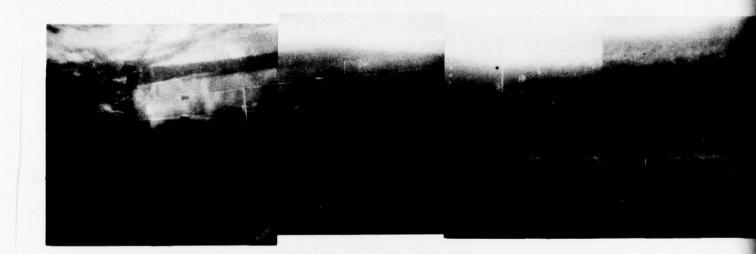
During the next report period, the reduction of data will continue and the computer program for computer plots of all reduced data will be completed.

2. UNDERWATER PHOTOGRAPHY

Processing and duplicating of film data from PURVIS I trials was 90% completed during April. Copies of the 16mm color movie film data were sent to NEL and DTMB as requested. Most of the material has been initially analyzed for qualitative observations. Detailed analysis of selected runs was continued. A letter outlining the preliminary report was sent to S. Crump on April 28, 1966. The report itself will be submitted at the end of May. 12

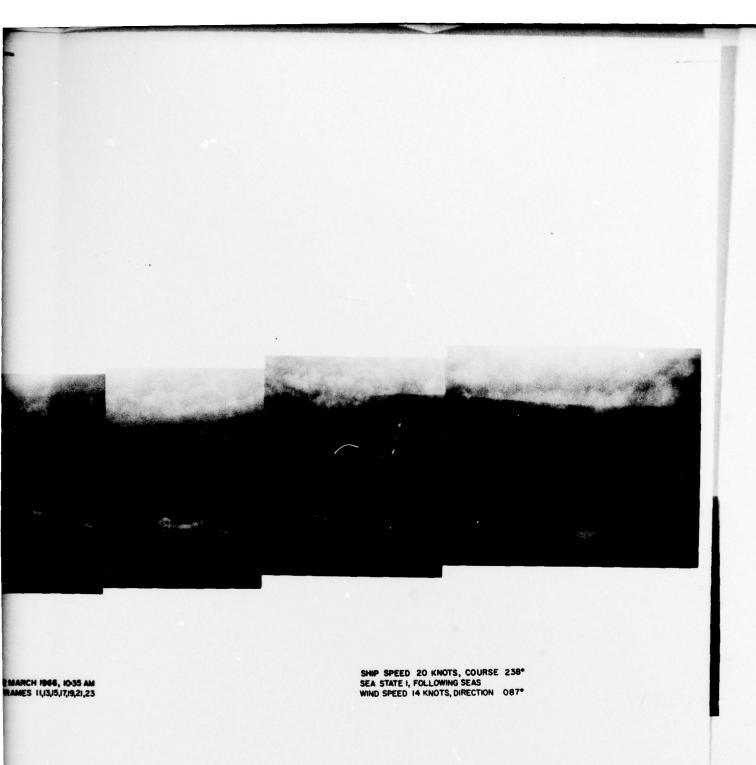
On the next page we show a trial mosaic assembled from the PURVIS I data. This is a sequential mosaic, that is, a mosaic made up from a sequence of frames from one (relatively) fixed platform camera (35mm black and white film). In this case, the frames came from camera No. 3 for Run 108 of 22 March 1966. The ship, sea and wind conditions are as indicated below the mosaic photograph. In the mosaic, we can see the port side of the PURVIS. The lower grid line extends across the entire mosaic to about Frame 88. The bilge keel can be seen in the upper right. It appears that naturally formed bubbles (or bubble clouds) are swept below the water surface at about Frame 20 and then swept aft along the hull to the bilge keel location. It also appears that bubbles on the starboard side may be seen in the lower right. This mosaic is only an example of the photographic data reduction, analysis and presentation to be carried out with the PURVIS I trial results.

Discussions were held with DTMB, J. Greenberg, and others concerning plans for PURVIS II trials. A test plan and



SEQUENTIAL MOSAIC

RUN NO. 108 - 22 MARCH 1966, 10 CAMERA NO.3, FRAMES 11,13,15,17,10



procedure was agreed upon and a preliminary proposal submitted to DTMB. The final proposal was 80% completed and will be submitted in early May.

3. ACOUSTIC TESTS, PURVIS I

A preliminary draft of an interim report on PURVIS I acoustic tests 11 has been prepared and submitted. It is anticipated that this final version of this report will be submitted as a DTMB report.

4. HYDROPHONES

A final configuration for the hydrophones for PURVIS II was tested and accepted by Fred Schloss of DTMB on April 25, 1966. Assembly and testing of hydrophones has begun with the first 21 units slated for delivery to BNS on May 9, 1966.

5. PURVIS II STRUTS

The second fixed strut for PURVIS II, as requested by I. Cook of DTMB was fabricated and shipped to BNS. Both struts have now been delivered. A fairing for the intersection of the strut and ship was fabricated and delivered to BNS.

6. SEA CHESTS

Sea Chests for PURVIS II were modified and shipped to BNS.

7. PREAMPLIFIERS

60 preamplifiers were tested and shipped to BNS. A final report describing PURVIS II preamplifier test results was submitted to NEL13

7200: HULL STUDIES

Testing of various cylindrical resonators is being continued in order to evolve an efficient design for a sea chest with required dynamic response. Ascertained to date is the fact that hollow cylinders of small diameter act as solid cylinders when both are used as quarter wave length resonators.

7600: HYDRODYNAMIC SUPPORT

Work on low-drag ship design, using quadrilateral source distributions, was continued.

Davidson Laboratory, working under subcontract, has started work on a bubble emitter for the flow visualization model tests.

9000 -- PROGRAM MANAGEMENT AND SYSTEM ENGINEERING

9100: PROGRAM MANAGEMENT AND SYSTEM ENGINEERING

During the month of April, the program was revised to reflect redirection of the DUMILOAD Education Program, and to include activities for the transducer heat problem and TRG's input to the GD ARAB Program. In addition, the front end electronics, WP 21-1 and -2 were terminated by NEL and have been deleted from the program.

The NEL PERT Time and cost reports have been updated, for the month.

TRG received NEL's letter SS 048 001 (08537), dated April 19th, and all suggestions and requests for information will be answered.

The following technical reports were mailed to NEL during April:

TM-66-12 Tolerances for Array Element Excitations Based on Sidelobe Ratios, V. Mangulis

TM-66-10 On the Choice of Beam Spacing in Rotational Direc-

tional Transmission, A. Novick

TM-66-14 Properties of Transducer Array Inpedance Matrix and its Inverse, R. Wilson

TN-66-11 Results of Converter-Filter Test, J. Cabot

TM-66-9 PURVIS II Pre-Amplifier Test Results I, J. Golden

TN-66-9

Transducer Shock Testing, I. Melnick
Transducer Corrosion and Fouling Studies, R. Goldman TN-66-7

TN-66-10

TM-66-16

Report on Potentiostatic Tests, R. Goldman Interim Report on Sonar Performance, A. Novick Simplified System Performance Study (Revision B), A. Novick TM-66-3

Acceleration Sensitivity Test Results I, J. Golden TM-66-15

TM-66-18 Interim Report on ASW Simulation Computer Program, D. Cope

9300: ADVANCED ELECTRONIC TECHNIQUES

Measurements on the STL PRIMAG evaluation unit have been completed and a documentary report is 90% complete. A theoretical estimate of the effects of interchannel cross-talk on the beam patterns formed is being prepared for inclusion in the report, along with a preliminary beamformer design based on the results of these measurements. The report will be submitted during the month of May.

9400: ENVIRONMENTAL

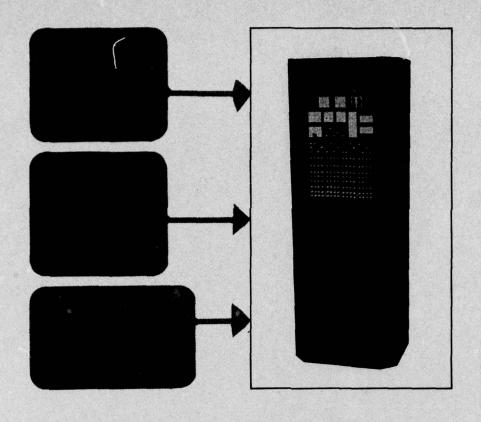
Work on WP 94-1 for the month of April 1966 consisted of the following:

- Continuation of water absorption tests on elastomeric materials in natural and synthetic sea water at ambient and elevated temperatures.
- 2. Immersion and efficiency tests on transducer elements located at Ocean City, N.J. were continued. This test will continue for an additional eight months.
- 3. Water vapor transmission test on elastomeric materials is continuing. It is expected that additional testing will continue for the next six months.
- 4. Reduced scale cathodic protection test under velocity conditions is continuing. This test will continue for an additional three months during which time sufficient data will have been collected to permit predictions to be made for long term protection.
- 5. Test panels for the cavitation experiments are being fabricated and the transducer components are being assembled. This experiment will determine the effect of operating the transducers at cavitation levels on the standard Navy anticorrosion and antifouling coatings.

6. Technical report on potentiostatic tests was submitted to NEL. 14

REFERENCES:

- 1. "On the Choice of Beam Spacing in Rotational Directional Transmission," A. Novick, 023-TM-66-11, April 1966.
- "Interim Report on the Surface-Duct Propagation Model for C/P Sonar Predictions," A. Novick, 023-TM-66-24; May 1966.
- 3. "Interim Report on Sonar Performance," CONFIDENTIAL, A. Novick, 023-TM-66-16, April 1966.
- "On Sonar Performance Estimation for Remote Source and Receiver," R. Seegal and A. Novick, 023-TM-66-23, May 1966.
- 5. "Simplified System Performance Study," Revision B, A. Novick, 023-TM-66-3.
- 6. "The Effect of Bottom Slope on Bottom Bounce Echo Ranges," A. Lehmann, 023-TM-66-25, May 1966.
- 7. "Mathematical Techniques for Cost-Effectivenss Optimization," L. Chin, 023-TM-66-21, May 1966.
- 8. "Analysis of Results of STL PRIMAG," J. Franceschini, June 1966.
- 9. "Fault Isolation and Self-Checking Equipment in C/P Sonar," D. Cox, 023-TM-66-22, May 1966
- "Results of Converter-Filter Test," J. Cabot, 023-TN-66-11, April 1966.
- 11. "Interim Report on PURVIS I Acoustic Tests," S. Gardner, 023-TM-66-19, May 1966.
- 12. "Initial Photographic Data Reduction for PURVIS I Sea Trials," A. Raff, May 1966.
- 13. "PURVIS II Preamplifier Test Results I," J. Golden, 023-TM-66-9, May 1966.
- 14. "Report on Potentiostatic Tests," R. Goldman, 023-TN-66-10, April 1966.



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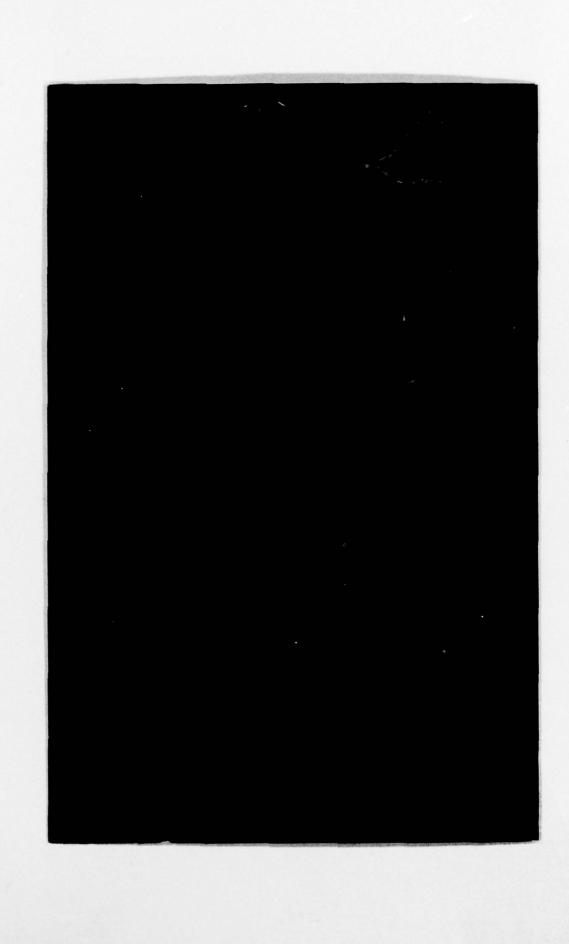
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